#### Supporting both Range Queries and Frequency Estimation with Local Differential Privacy

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#### Overview

- Background
- Privacy Notions and Mechanisms
- Problem Formulation
- The Proposed Mechanism
- Frequency Estimation Protocol
- Evaluation
- Conclusion

# Background

• Companies are collecting our private data to provide better services.



• However, private data collection raises privacy concerns.

#### Privacy Concerns

Moreover, privacy leakage might be occurred even erasing users' identifiers before releasing the data.

#### Companies need to carefully release users' data for analysis.

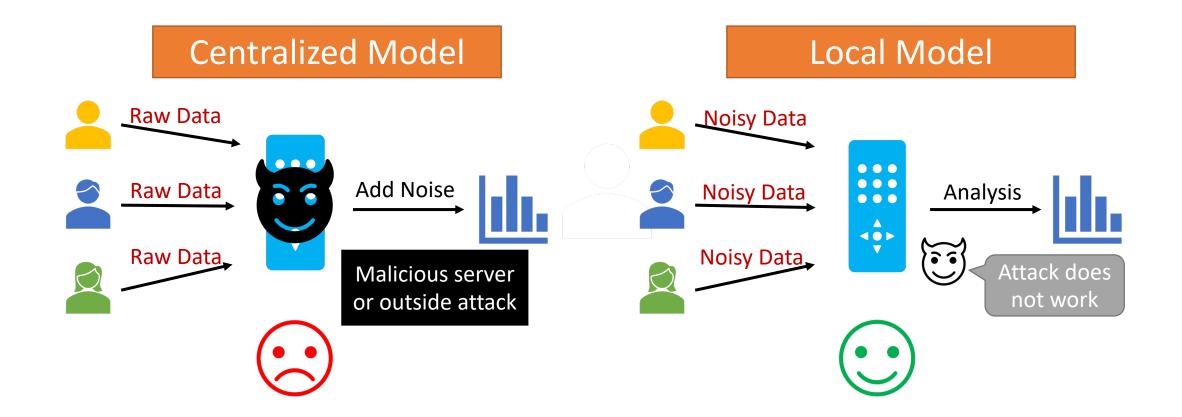
Privacy lawsuit of Netflix Prize

Source: Wikipedia

Note: These percentages reflect all respondents who, on a scale of 1-5 rated their concern as a 5 (Extremely concerned) or 4 (Very Concerned) with Source: Consumer Perceptions of Privacy in the Internet of Things, Altimeter Group, 2015 Base: n=2062 respondents

Source: https://jessgroopman.wordpress.com/2015/07/30/how-does-your-business-perform-against-consumers-biggest-privacy-concerns/

#### Centralized and Local Privacy Models



• The local model is more secure than the centralized one.

### Local Differential Privacy (LDP)

A mechanism M satisfies  $\epsilon$ -LDP iff for any pair of inputs x, x' and any output y

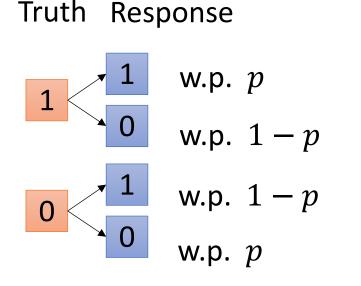
$$\frac{\Pr(M(x) = y)}{\Pr(M(x') = y)} \le e^{\epsilon}$$

- *x*, *x*': the raw data (only in user-side);
- y: the perturbed data (can be published and known by adversary).
- $\epsilon$ : privacy budget (the smaller  $\epsilon$  indicates the stronger privacy)

Intuitively, given any output y of a mechanism M, an adversary cannot infer whether the input is x or x' with high confidence (controlled by  $\epsilon$ ).

#### Mechanisms under LDP [for frequency estimation]

- Randomized Response (RR) [Warner, 1965]: reports the truth with specified probability; (binary answer)
- Example: are you wearing glasses?



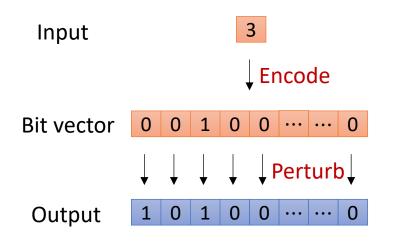
Expectation of observed frequency:  $E[f] = f^*p + (1 - f^*)(1 - p)$   $= (2p - 1)f^* + (1 - p)$ 

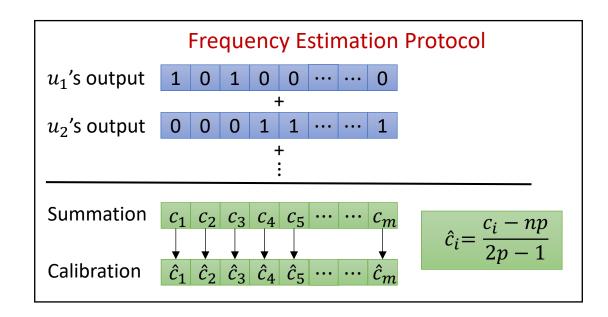
Calibration: 
$$\hat{f} = \frac{f - (1 - p)}{2p - 1}$$

Unbiased estimator:  $E[\hat{f}] = f^*$ 

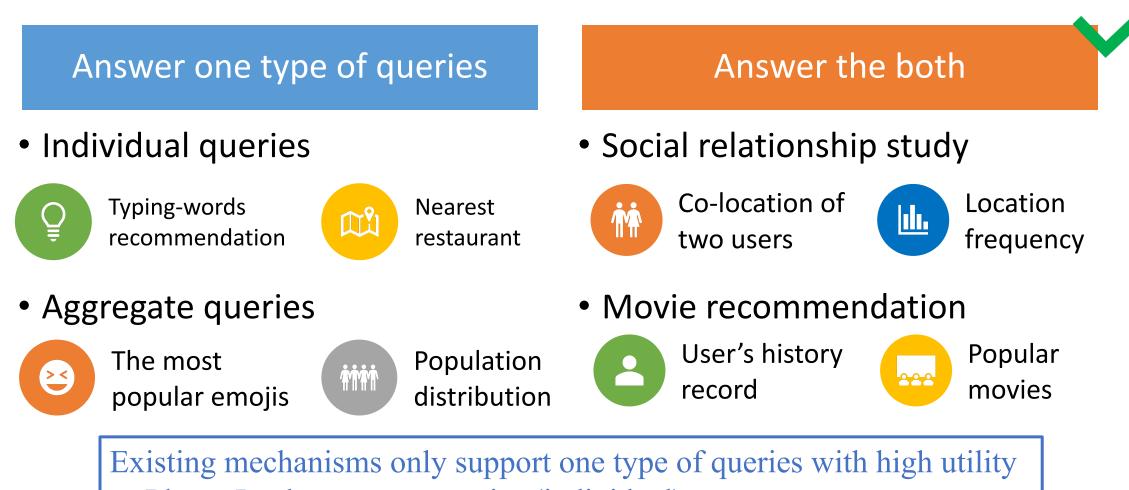
#### Extend RR for General Cases

- RAPPOR [CCS'14]: encodes the input into a bit vector and flips each bit with specified probability;
- Example: what's your favorite color ? (among 10 options)





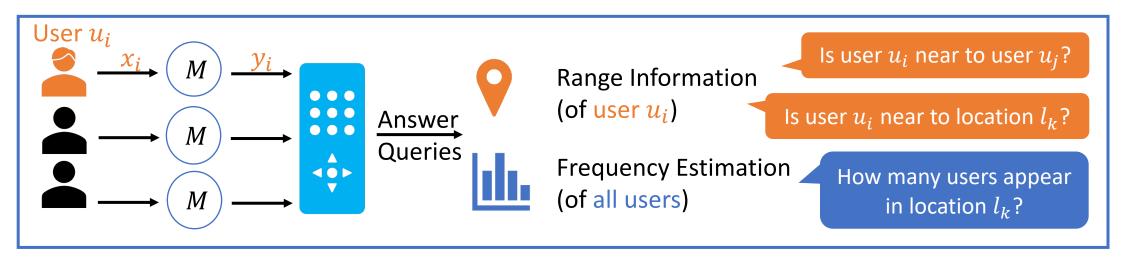
### Motivation



- Planar Laplace: range queries (individual);
- RR, RAPPOR, and OUE: frequency estimation (aggregate).

#### **Problem Formulation**

- The input/output domain contains m items, indexed by  $I = \{1, 2, \dots, m\}$ ;
- There are *n* users, where each user  $u_i$  independently perturbs her raw data  $x_i$  into  $y_i$  and uploads  $y_i$  to the server;
- The server answers two types of queries: 1. range query such as POI (points of interest) search; 2. frequency estimation (aggregate information).



#### Privacy Notions: LDP and local d-privacy

- Problem of LDP notion: it does not consider the distance between items (thus it will lead to bad utility of range query).
- Solution: local d-privacy (a variant of LDP with distance metric).

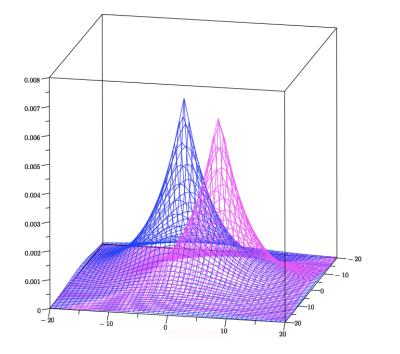
$$\frac{\Pr(M(x) = y)}{\Pr(M(x') = y)} \le e^{\epsilon \cdot d(x,x')}$$

where  $d(\cdot, \cdot)$  can be any distance metric with triangle inequality, i.e.,  $d(x, x') + d(x, x'') \ge d(x', x'')$ .

The distance metric in local d-privacy relaxes the strong privacy constraint of LDP, thus can provide better utility

### Existing Mechanisms under Local d-privacy

- Planar Laplace [CCS' 13]
- Only under Euclidean distance (i.e., the notion of geo-indistinguishability)
- Not designed for frequency estimation



• Optimization-based mechanism [ICDCIT 2015]

Idea: obtain the optimal perturbation probability matrix by minimizing the linear objective function with required privacy constraints.

Problem: 1. the dimension issue of solving the optimization problem; 2. for frequency estimation, the theoretical utility depends on true frequencies with non-linear correlation.

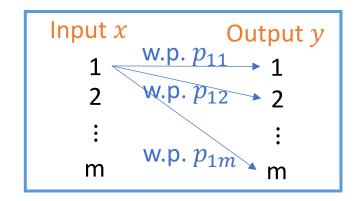
## Problem of Existing Mechanisms

- Randomized Response (RR) based mechanisms (under LDP) do not consider distance;
  bad utility on range query
- Planar Laplace Mechanism (under local d-privacy) does not consider aggregate information;
  bad utility on frequency estimation
- In optimization-based mechanism, the objective function (frequency estimation) is hard to evaluate and solving the optimization problem takes high computation cost.

Our solution: combine the idea of RR and Planar Laplace.

## Our Mechanism

Privacy constraint of local d-privacy:  $p_{ik}/p_{jk} \le e^{\epsilon d_{ij}} (\forall i, j, k)$ where  $p_{ik} = \Pr(y = k | x = i)$ 



- Let  $p_{jk} = e^{-\epsilon q_{jk}} \cdot p_{kk}$  for  $j \neq k$ . (intuition: make  $p_{jk}$  as small as possible)
- Let  $\sum_{k=1}^{m} p_{jk} = 1$  for all *j*. (the summation of probabilities from the same input should be 1)

Combining the above two equations, we can first compute  $p_{kk}$  by solving *m*-dimensional linear equations, then compute  $p_{jk} = e^{-\epsilon d_{jk}} \cdot p_{kk}$ .

#### Properties of Our Mechanism

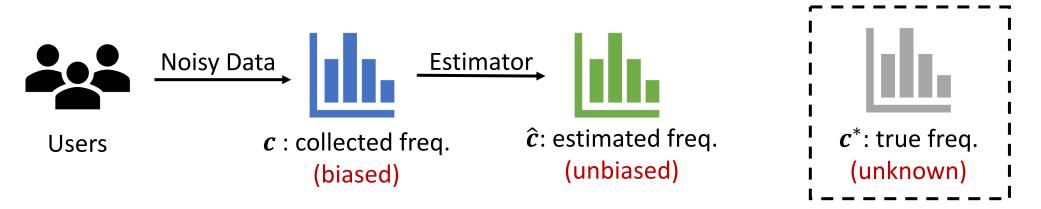
It satisfies local d-privacy (by triangle inequality of distance metric).

$$\frac{p_{ik}}{p_{jk}} = \frac{p_{kk}}{p_{jk}} \cdot \frac{p_{ik}}{p_{kk}} = e^{\epsilon \left(d_{jk} - d_{ik}\right)} \le e^{\epsilon d_{ij}}$$

It is the optimal solution when the objective function is  $f = \sum_{k=1}^{m} p_{kk}$ .

- This objective function corresponds to co-location queries;
- This property is proved by Karush-Kuhn-Tucker (KKT) Conditions.





- Result needs calibration (by estimator) since perturbation is biased;
- The frequency estimation protocol in LDP does not work in our case.

Frequency estimator for our mechanism:  $\hat{c} = (\mathbf{P}^T)^{-1} c$ , where  $\mathbf{E}[\hat{c}] = c^*$ .

Theoretical mean square error: MSE=Var[ $\hat{c}$ ] (related to true freq.  $c^*$ ).

#### Evaluation

#### Theoretical

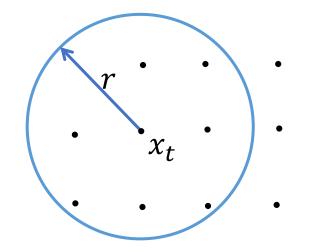
• Error<sub>range</sub> = 
$$\sum_{t=1}^{n} (1 - \sum_{y_t \in R(x_t, r)} p_{x_t y_t})$$

• 
$$MSE_{freq} = \sum_{k=1}^{m} \sum_{j=1}^{m} (c_j^* \sum_{i=1}^{m} q_{ki}^2 p_{ji}) - n$$

#### Simulation

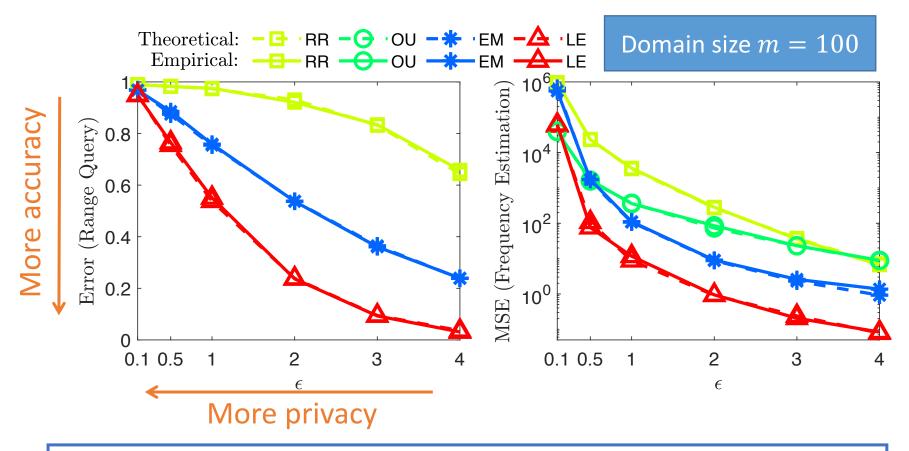
• Error<sub>range</sub> = 
$$\sum_{t=1}^{n} (1 - \mathbf{1}_{R(x_t,r)}(y_t))$$
  
• MSE<sub>freq</sub> =  $\sum_{k=1}^{m} (\hat{c}_k - c_k^*)^2$ 

Range query evaluation: how accurate of output



$$R(x_t, r) = \{k | k \in I, d(k, x_t) \le r\}$$
  
$$\mathbf{1}_{R(x_t, r)}(y_t) = \begin{cases} 1, y_t \in R(x_t, r) \\ 0, y_t \notin R(x_t, r) \end{cases}$$

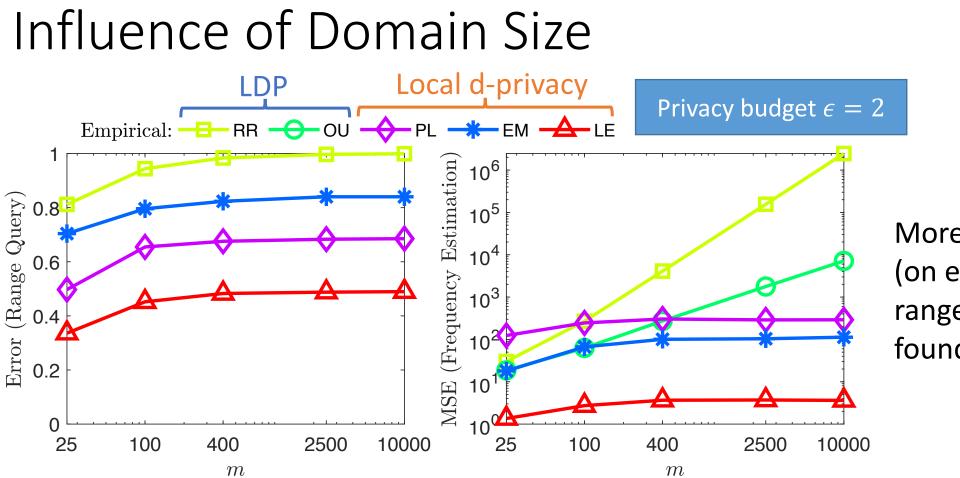
#### Synthetic Data



#### LE: our mechanism

• OU only supports freq. estimation

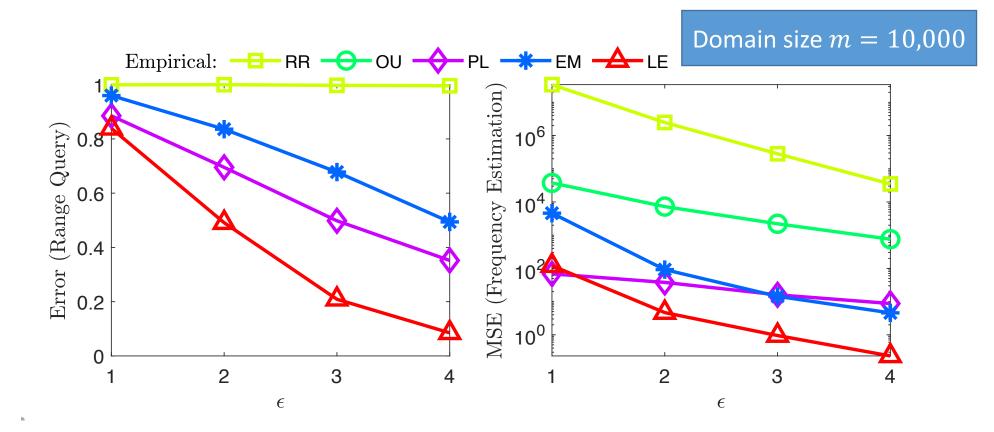
Observations: 1. The theoretical analysis is effective; 2. Our mechanism (LE) outperforms other ones.



More experiments (on estimator and range size) can be found in our paper.

Observations: 1. For LDP mechanisms,  $MSE_{freq}$  is proportional to domain size; 2. For local d-privacy mechanisms, domain size has little influence.

#### Real-world Location Data [Gowalla]



Similar observations!

#### Conclusion

- We tackle the problem of supporting both range query and frequency estimation with high utility at the the same time;
- We adopt the notion of local d-privacy instead of LDP to obtain better utility and design our mechanism by combining the idea of randomized response mechanism and Planar Laplace;
- Our mechanism only needs to solve a linear equation which has less computation complexity than optimization-based mechanism.
- Simulation results show the effectiveness of our mechanism and the advantage of local d-privacy (the notion with distance metric)

Future work: support complex data types (e.g., set-valued data) and complex analysis tasks (e.g., frequent items mining).

# Thank You!

**Questions & Answers**